



دانشگاه علم و صنعت ایران

دانشکده مهندسی کامپیوتر

عنوان درس:

طراحی نرم افزارهای اتکاء پذیر (Dependable Software Design)

تحلیل با استفاده از شبکه های پاداش تصادفی

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Reference

- **M.R. Lyu, *Software Fault Tolerance*, John Wiley & Sons (1995)**

- Chapter 6: Analyses using Stochastic Reward Nets (SRNs)**

- **Outline:**

- 1. Stochastic Reward Nets**

- 2. Fault Tolerant Software Models**

- 3. Dependencies in the SRN Models**

1. Stochastic Reward Nets

- **Stochastic reward nets (SRNs)** are a generalization of generalized stochastic Petri nets (GSPNs), which in turn are a generalization of stochastic Petri nets (SPNs).
- SRNs substantially increase the modeling power of the GSPN by adding *guard functions*, *marking dependent arc multiplicities*, *general transition priorities*, and *reward rates at the net level*.

1. Stochastic Reward Nets

- A *guard function* is a Boolean function associated with a transition [Cia89, Cia92].
 - Whenever the transition satisfies all the input and inhibitor conditions in a marking M , the guard is evaluated.
 - The transition is considered enabled only if the guard function evaluates to *true*.

1. Stochastic Reward Nets

- *Marking dependent arc multiplicities* allow
 - either the number of tokens required for the transition to be enabled, or
 - the number of tokens removed from the input place, or
 - the number of tokens placed in an output place to be a function of the current marking of the PN.
- Such arcs are called *variable cardinality arcs*.

Measures

- **Stochastic Reward Nets (SRNs) provide the same modeling capability as Markov reward models (MRMs).**
- **A *Markov reward model* is a Markov chain with reward rates (*real* numbers) assigned to each state.**
- **A state of an SRN is actually a marking**
 - **labeled $(\#(P_1), \#(P_2), \dots, \#(P_n))$ if there are n places in the net.**

Measures

- We label the set of all possible markings that can be reached in the net as Ω .
- These markings are subdivided into tangible markings Ω_T and vanishing markings Ω_V .
- For each tangible marking i in Ω_T , a reward rate r_i is assigned.
- This reward is determined by examining the overall measures to be obtained.
- In Section 6.5, we examine the reward definitions needed to generate reliability, safety, and performance measures.

Measures

- **Several measures are obtained using Markov reward models.**
- **These include:**
 - **the expected reward rate both in steady state and at a given time,**
 - **the expected accumulated reward until either absorption (جذب) (بی‌نهایت) or a given time, and**
 - **the distribution of accumulated reward either until absorption or a given time.**

Measures

- The *expected reward rate in steady state* can be computed using the steady state probability of being in each marking i for all $i \in \Omega_T$.
- For steady state distribution i , the expected reward rate is given by

$$E[\mathcal{R}] = \sum_{i \in \Omega_T} r_i \pi_i$$

Measures

- The *expected reward rate at time t* can be computed by using the transient probability of being in each marking $i \in \Omega_T$, labeled $p_i(t)$.

- The expected reward rate at time t is then given by

$$E[\mathcal{R}(t)] = \sum_{i \in \Omega_T} r_i p_i(t)$$

- The *distribution of reward rate at time t* denoted by $P\{R(t) \leq x\}$ is given by

$$P\{\mathcal{R}(t) \leq x\} = \sum_{r_i \leq x, i \in \Omega_T} p_i(t)$$

Measures

- The *accumulated reward* in $(0, t]$, $Y(t)$, is denoted as

$$Y(t) = \int_0^t \mathcal{R}(u) du.$$

- The *expected accumulated reward* in $(0, t]$ can be computed as

$$E[Y(t)] = E\left[\int_0^t \mathcal{R}(u) du\right] = \int_0^t E[\mathcal{R}(u)] du = \sum_{i \in \Omega_{\mathcal{T}}} r_i \int_0^t p_i(u) du$$

Measures

- The *expected accumulated reward until absorption*, labeled $E[Y(\infty)]$, can be computed as

$$E[Y(\infty)] = \sum_{i \in \Omega_T} r_i \int_0^{\infty} p_i(u) du$$

Measures

- The *distribution of accumulated reward* is a measure of considerable interest.
- The distribution of accumulated reward until absorption is denoted as

$$\mathcal{Y}(x) = P\{Y(\infty) \leq x\}.$$

- This distribution was first studied by Beaudry [Bea78] for an underlying CTMC model with strictly positive reward rates, and was extended by Ciardo et al. [Cia90] to allow an underlying semi-Markov model with non-negative reward rates.

2. Fault Tolerant Software Models

- Next, we develop SRN models for
 - recovery blocks,
 - N-version programming blocks, and
 - N self-checking programming blocks.
- In this section, we focus on the basic model.
- We revisit each model in Section 6.4 to discuss issues such as *detected* versus *undetected failures* and *common-mode* versus *separate failures*.

Recovery Blocks

- A **recovery block** (RB) consists of two or more **variants** and a **single acceptance test** (AT).
- The variants are ordered with the first variant called the *primary* and the others called *alternates*.
- The primary and the alternate variants are independently developed, based on different algorithms and implemented by different programmers.

Recovery Blocks

- For each input to the recovery block, the primary is executed first and its output is evaluated using the AT.
- If the AT fails to accept the output, a rollback recovery is attempted; this process is repeated for each alternate variant in succession until either
 1. a variant produces an output that is accepted by the AT,
 2. the rollback recovery fails, or
 3. all variants execute without satisfying the AT.
- In the last case, the RB is said to have failed on this input dataset.

Recovery Blocks

- The pseudocode for a RB with N variants (a primary and $N-1$ alternates) is shown below:

```
ensure acceptance test  
  by primary variant (#1)  
  else by alternate variant (#2)  
  else by alternate variant (#3)  
  ...  
  else by alternate variant (#N)  
else error
```

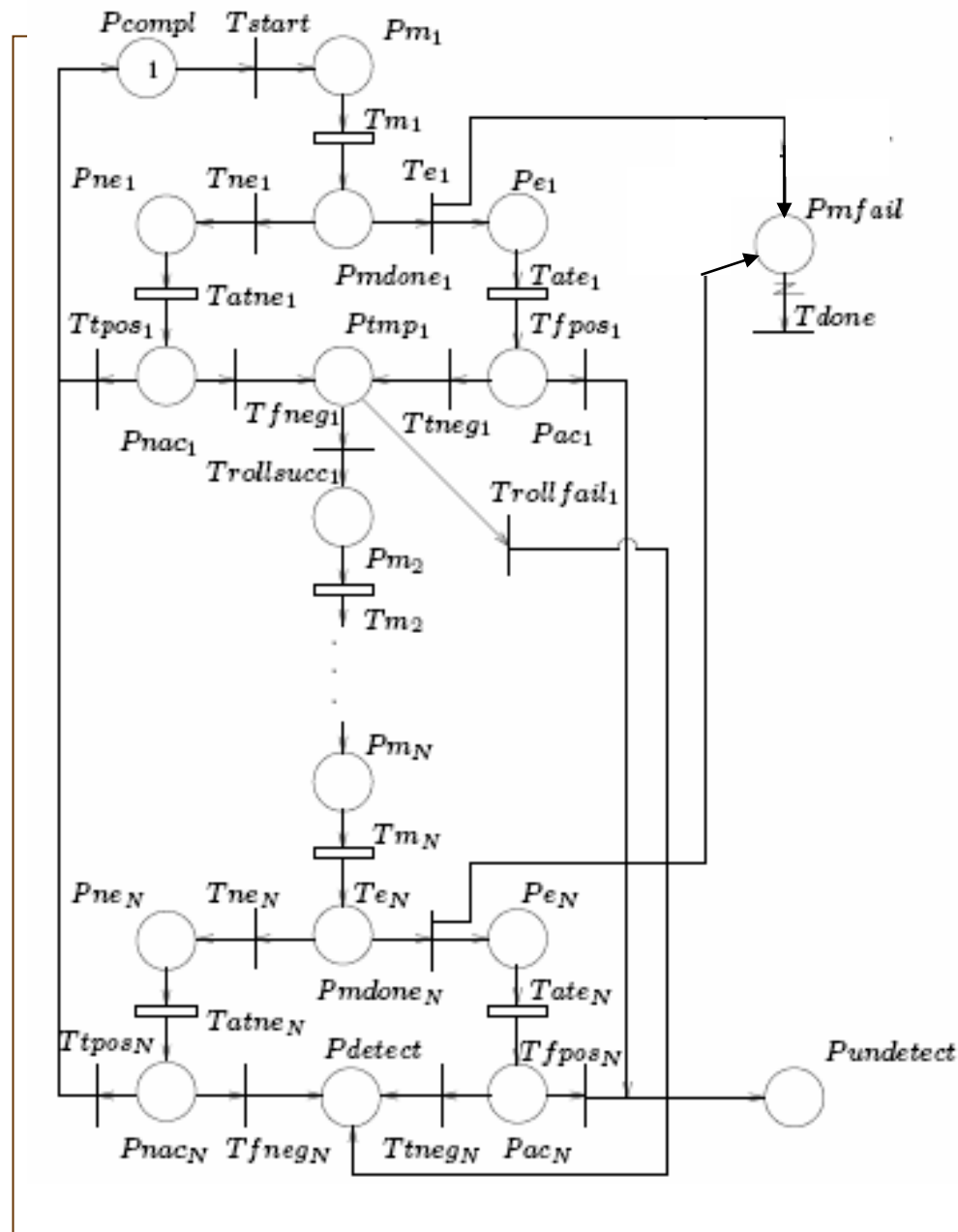
Recovery Blocks

- The parameters required for a recovery block model are difficult to obtain.
- Following the categories of Pucci [Puc90, Puc92], events in the recovery blocks are classified into the following four types of events.
 1. *Variant i* produces correct output which the AT accepts.
 2. *Variant i* produces correct output which the AT rejects.
 3. *Variant i* produces incorrect output which the AT rejects.
 4. *Variant i* produces incorrect output which the AT accepts.

Recovery Blocks

- In addition, we will consider both successful and unsuccessful rollback recovery attempts following a negative AT diagnosis.
- The SRN model of a recovery block is shown in Figure 6.1.

Recovery Blocks



Transition	Trans. Priority
T_{done}	HIGH

Transition	Guard Function
T_{done}	$\#(P_{compl}) > 0$

Arc	Arc Multiplicity
$P_{mfail} \rightarrow T_{done}$	$\max(\#(P_{mfail}), 1)$

Recovery Blocks

- The net is nearly *self-explanatory* (!).
- Place P_{compl} is the starting point of the RB.
 - compl => completion
- The firing of transition T_{start} , which places a token in place P_{m_1} , indicates that the recovery block has begun executing the next (or first in this case) dataset.
- A token in place P_{m_1} indicates that the primary variant in the recovery block has begun execution on the current dataset.

Recovery Blocks

- The firing of transition T_{m_1} corresponds to the completion of the execution of the primary variant.
- Transitions T_{ne_1} and T_{e_1} correspond to the events that the output produced by the variant are correct and incorrect respectively.
- Transition T_{ne_1} moves the token from place P_{mdone_1} to place P_{ne_1} indicating that the variant produced a correct output.

Recovery Blocks

- Transition T_{e_1} moves the token from place P_{mdone_1} to both places P_{e_1} and P_{mfail} .
- A token in place P_{e_1} indicates that the first variant produced an incorrect output.
- Place P_{mfail} counts the number of variants producing an incorrect result on the current dataset; this is needed to represent common-mode failures.

Recovery Blocks

- Transition T_{atne_1} represents the execution of the AT after the variant produces a correct output.
- The immediate transitions T_{tpos_1} and T_{fneg_1} , which correspond to a correct positive diagnosis by the AT and a false negative diagnosis by the AT respectively, are then enabled.
- Transition T_{ate_1} represents the execution of the AT after the variant produces an incorrect output.

Recovery Blocks

- The immediate transitions T_{tnegl} and T_{fposl} , which correspond to correct negative diagnosis by the AT and a false positive diagnosis by the AT respectively, are then enabled.
- A false positive AT diagnosis causes the token to be moved to place $P_{undetct}$ indicating an undetected block failure.
- A true positive AT diagnosis causes the token to be moved to place P_{compl} indicating the block has completed execution on the current dataset.
- The block then begins operation on the next dataset.

Recovery Blocks

- If an error is discovered, represented by the firing of either T_{fneg_1} and T_{tneg_1} , the system initiates a rollback recovery action.
- Transition $T_{rollsucc_1}$ represents a successful rollback.
- Transition $T_{rollfail_1}$ represents an unsuccessful rollback resulting in an RB failure.
- The output arc from $T_{rollsucc_1}$ leads to P_{m2} , the starting place of the rst alternate variant, while the output arc from $T_{rollfail_1}$ leads to P_{detect} which represents a detected RB failure.

Recovery Blocks

- The alternate variants are similarly modeled by the other places and transitions indexed from 2 to N .
- The structure of the last variant is slightly different, since the failure of the last variant automatically results in a detected system failure.
- Thus, the output arcs from transitions T_{fneg_N} and T_{tneg_N} lead to place P_{detect} .

Recovery Blocks

- When the recovery block completes (the token is returned to place P_{m1}) then transition T_{done} fires and all tokens are removed from place P_{mfail} for the next execution of the recovery block.

N-Version Programming

- In N-version programming (NVP), all variants operate on the same input in parallel.
- The results of all variants are collected and a voter determines the system output [Avi85].
- The reliability of this mechanism is dependent upon individual variant results.
 - If more than half of the variants produce results that are within the required error tolerance, the prevailing result (نتیجه غالب) is declared correct.
 - If half or less than half of the variants produce the same result, the result is declared incorrect. In this case, no output would be released by the block.

N-Version Programming

- In Figure 6.2, an SRN model of an N-version programming system is shown...

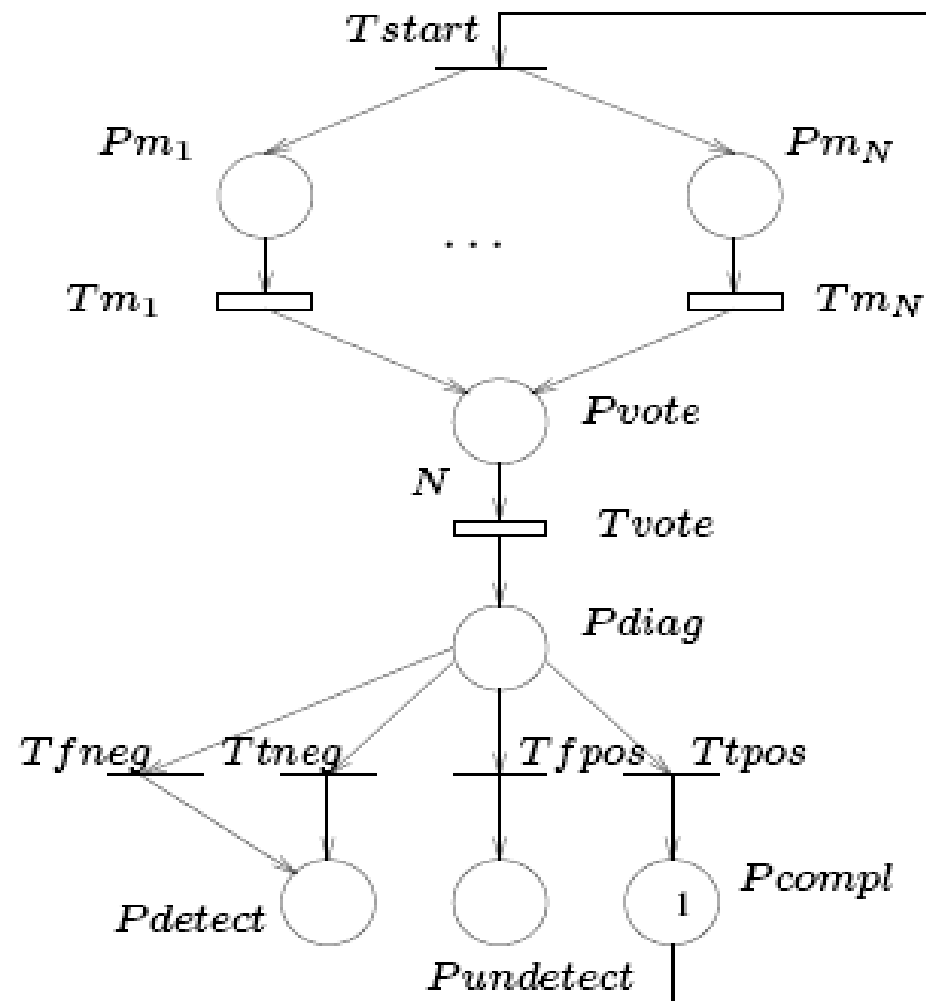


Figure 6.2 SRN model of N -version programming

N-Version Programming

- Initially, a single token is in place P_{compl} .
- The software block begins operating on the next input immediately with the firing of transition T_{start} .
- This transition places one token in each of the places $P_{m_1}, P_{m_2}, \dots, P_{m_N}$, representing the fact that each variant begins operation on the provided input.
- Transitions T_{m_i} for $i \in 1, 2, \dots, N$ represents the completion of execution of variant i .

N-Version Programming

- When all variants have completed, place P_{vote} will contain N tokens, enabling transition T_{vote} .
- Transition T_{vote} represents the execution of the voting mechanism.
- When voting is complete, a single token is moved to place P_{diag} where the voting result is diagnosed.
- If less than half of the variants produced correct output, then the voting result can be either a **true negative**, represented by the firing of transition T_{tneg} , or a **false positive**, represented by the firing of transition T_{fpos} .

N-Version Programming

- If at least half of the variants produced correct output, then the voting result can be either a **true positive**, represented by the firing of transition T_{tpos} , or a **false negative**, represented by the firing of transition T_{fneg} .
- If the voting result is negative, either transition T_{tneg} or transition T_{fneg} fire, moving the token to place P_{detect} .
 - **This represents a detected error.**

N-Version Programming

- If the voting result is a false positive, transition T_{fpos} fires, moving the token to place $P_{undetected}$, **indicating an undetected error.**
- If the voting result is a true positive, transition T_{tpos} fires, moving the token to place P_{compl} , **indicating the software block as successfully completed execution on the current dataset.**
- Once the token is returned to place P_{compl} , the N -version programming block begins operating on the next input.

N Self-Checking Programming

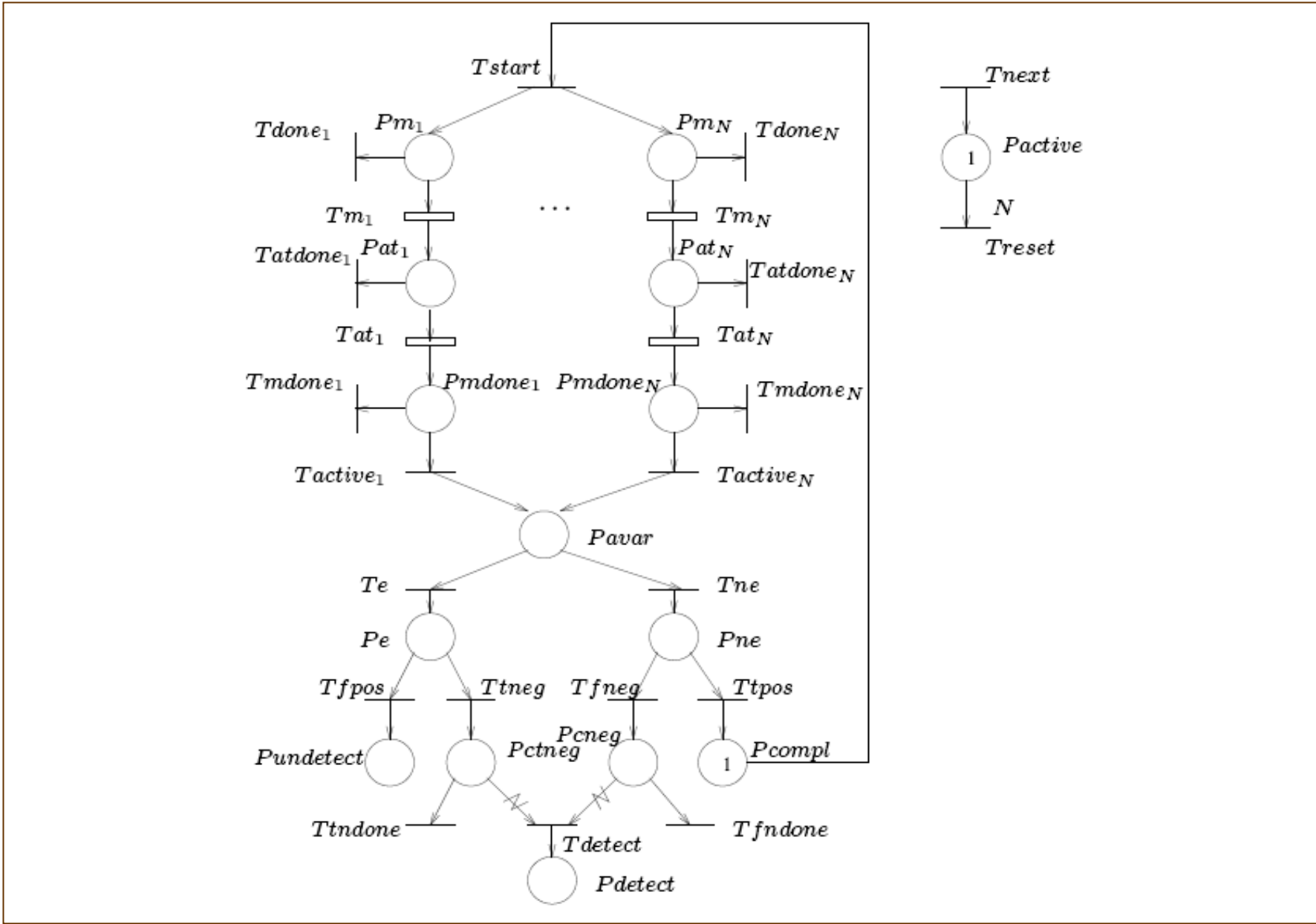
- In *N self-checking programming (NSCP)*, all variants operate in parallel on the same input.
- There are two possible decision mechanisms [Lap90] using this technique:
 - The first possibility is that each variant has its own **acceptance test**.
 - The second possibility is that each pair of variants is compared using a **comparison algorithm** associated with the pair.

N Self-Checking Programming

- In each of the above possibilities, the acceptance test associated with each variant or comparison algorithm associated with a pair of variants can be **identical** or **independently derived** (به طور مستقل، طبق تنوع طراحی حاصل شده باشند).
- One variant is always considered to be the **active variant**.
 - If the active variant produces an output that is diagnosed as correct, then that output is the block output.
 - If the active variant diagnoses its output to be incorrect, then the status of active variant is passed to one of the **alternate variants**.

NSCP with Acceptance Test

- First, we study the case where each variant diagnoses the correctness or incorrectness of its output using an acceptance test as shown in Figure 6.3.
- The transition priorities, guard functions, and arc multiplicities associated with this model are given in Figure 6.4.



Transition	Trans. Priority
T_{next}	LOW
T_{reset}	HIGH
T_{start}	LOW
T_{active_i} , for $i \in [1, N]$	HIGH
T_{detect}	HIGH
T_{done_i} , for $i \in [1, N]$	HIGH
T_{atdone_i} , for $i \in [1, N]$	HIGH
T_{mdone_i} , for $i \in [1, N]$	HIGH
T_{tndone}	HIGH
T_{fndone}	HIGH

Transition	Guard Function
T_{next}	$\#(P_{m_i}) + \#(P_{at_i}) + \#(P_{mdone_i}) + \#(P_{avar}) + \#(P_e) + \#(P_{ne}) + \#(P_{detect}) + \#(P_{undetected}) + \#(P_{compl}) == 0$ where $i = \#(P_{active})$
T_{reset}	$\#(P_{active}) > N$
T_{active_i} , for $i \in [1, N]$	$\#(P_{active}) == i$
T_{detect}	$\#(P_{ctneg}) + \#(P_{cfneg}) == N$
T_{done_i} , for $i \in [1, N]$	$\#(P_{compl}) + \#(P_{detect}) + \#(P_{undetected}) > 0$
T_{atdone_i} , for $i \in [1, N]$	$\#(P_{compl}) + \#(P_{detect}) + \#(P_{undetected}) > 0$
T_{mdone_i} , for $i \in [1, N]$	$\#(P_{compl}) + \#(P_{detect}) + \#(P_{undetected}) > 0$
T_{fndone}	$\#(P_{compl}) + \#(P_{detect}) + \#(P_{undetected}) > 0$
T_{tndone}	$\#(P_{compl}) + \#(P_{detect}) + \#(P_{undetected}) > 0$

Arc	Arc Multiplicity
$P_{ctneg} \rightarrow T_{detect}$	$\#(P_{ctneg})$
$P_{cfneg} \rightarrow T_{detect}$	$\#(P_{cfneg})$
$P_{ctneg} \rightarrow T_{tndone}$	$\max(\#(P_{ctneg}), 1)$
$P_{cfneg} \rightarrow T_{fndone}$	$\max(\#(P_{cfneg}), 1)$

NSCP with Acceptance Test

- Initially, there is a single token in both places P_{compl} and P_{active} .
- The software block begins operating on the next input immediately with the firing of transition T_{start} .
- This transition places one token in each of places P_{m1} , P_{m2} , ..., P_{mN} , representing the fact that each variant begins operation on the provided input.

NSCP with Acceptance Test

- Transitions T_{mi} for $i \in 1, 2, \dots, N$ represents the execution of each variant i .
- As each variant completes execution, a token is placed in P_{ati} (for variant i).
- The self-checking procedure (acceptance test execution) is modeled by transition T_{ati} .
- When the acceptance test completes, the token is moved from place P_{ati} to place P_{mdonei} (for variant i).

NSCP with Acceptance Test

- Place *Pactive* contains the number of tokens representing the number of the active variant (a number between 1 and N).
- When the active variant completes its acceptance test, then a token is in place *Pmdonei* enabling transition *Tactivei*, where i is the number of tokens in place *Pactive*.
- The firing of transition *Tactivei* moves the token to place *Pavar*.

NSCP with Acceptance Test

- This enables transitions Te , representing the fact that the active variant has produced incorrect output, and transition Tne , representing the fact that the variant has produced correct output.
- If the variant produced incorrect output, the firing of transition Te moves the token to place Pe .
- The diagnosis of incorrect output can be either a false positive diagnoses or a true negative diagnosis represented by transitions $Tfpos$ and $Ttneg$ respectively.

NSCP with Acceptance Test

- If a false positive diagnosis occurs, the token is moved to place *Pundetct*, representing an undetected error.
- If a true negative diagnosis is detected, the token is moved to place *Pctneg*.
- Place *Pctneg* counts the number of incorrect variant outputs which are diagnosed as true negative.
- The tokens remain in place *Pctneg* until either all variants are diagnosed as incorrect or the block completes execution without detecting a failure.

NSCP with Acceptance Test

- If the variant produced incorrect output, transition T_{ne} fires moving the token from place P_{avar} to place P_{ne} .
- The diagnosis of correct output can be either a false negative or a true positive represented by transitions T_{fneg} and T_{tpos} .
- Transition T_{fneg} moves the token from place P_{ne} to place P_{cfpos} .
- Place P_{cfpos} counts the number of correct variant outputs which are diagnosed as false negative.

NSCP with Acceptance Test

- The tokens remain in place $Pcfpos$ until either all variants are diagnosed as incorrect or the active variant pair diagnoses its output to be correct.
- If the sum of the number of tokens in place $Pctneg$ and $Pcfpos$ is equal to N , all variants have been diagnosed as incorrect.

NSCP with Acceptance Test

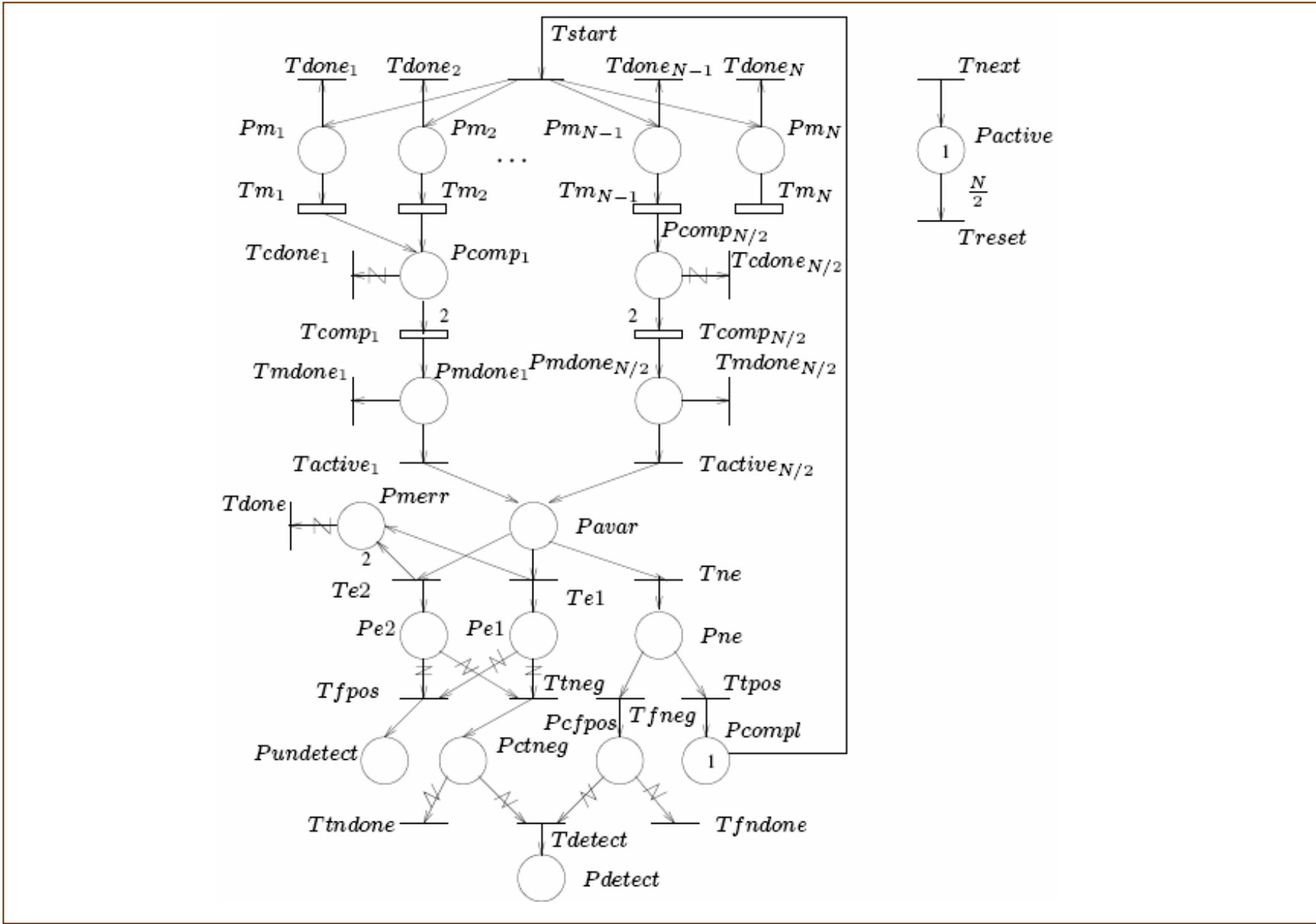
- This enables transition T_{detect} , which removes all tokens from places P_{ctneg} and P_{cfpos} and places a single token in place P_{detect} ; this represents a detected failure.
- If the diagnosis of the correct output is a true positive, transition T_{tpos} fires, moving the token from place P_{ne} to place P_{compl} .

NSCP with Acceptance Test

- A token in place P_{compl} satisfies the guard function for transitions T_{done_i} , T_{atdone_i} , and T_{mdone_i} for $i \in [1, N]$ and transitions T_{tndone} and T_{fndone} .
- All tokens in these places are removed from the net, effectively resetting the net to its initial state.
- After this reset, the N self-checking programming block begins execution of the next input.

NSCP with Comparison Algorithm

- Now, we study the case where the outputs of pairs of variants are diagnosed by a comparison algorithm as shown in Figure 6.5.
- The transition priority, guard, and arc multiplicity functions are given in Figure 6.6.



Transition	Trans. Priority
<i>Tnext</i>	LOW
<i>Treset</i>	HIGH
<i>Tstart</i>	LOW
<i>Tactive_i</i> , for $i \in [1, N/2]$	HIGH
<i>Tdetect</i>	HIGH
<i>Tdone_i</i> , for $i \in [1, N]$	HIGH
<i>Tcdone_i</i> , for $i \in [1, N/2]$	HIGH
<i>Tmdone_i</i> , for $i \in [1, N/2]$	HIGH
<i>Ttndone</i>	HIGH
<i>Tfndone</i>	HIGH
<i>Tedone</i>	HIGH

Transition	Guard Function
<i>Tnext</i>	$\#(Pm_{i \times 2}) + \#(Pcomp_i) + \#(Pmdone_i) + \#(Pavar) + \#(Pe) + \#(Pne) + \#(Pdetect) + \#(Pundetect) + \#(Pcompl) == 0$ where $i = \#(Pactive)$
<i>Treset</i>	$\#(Pactive) > N/2$
<i>Tactive_i</i> , for $i \in [1, N/2]$	$\#(Pactive) == i$
<i>Tfpos</i>	$\#(Pe1) + \#(Pe2) > 0$
<i>Ttneg</i>	$\#(Pe1) + \#(Pe2) > 0$
<i>Tdetect</i>	$\#(Pctneg) + \#(Pcfneg) == N/2$
<i>Tdone_i</i> , for $i \in [1, N]$	$\#(Pcompl) + \#(Pdetect) + \#(Pundetect) > 0$
<i>Tcdone_i</i> , for $i \in [1, N/2]$	$\#(Pcompl) + \#(Pdetect) + \#(Pundetect) > 0$
<i>Tmdone_i</i> , for $i \in [1, N/2]$	$\#(Pcompl) + \#(Pdetect) + \#(Pundetect) > 0$
<i>Ttndone</i>	$\#(Pcompl) + \#(Pdetect) + \#(Pundetect) > 0$
<i>Tfndone</i>	$\#(Pcompl) + \#(Pdetect) + \#(Pundetect) > 0$
<i>Tedone</i>	$\#(Pcompl) + \#(Pdetect) + \#(Pundetect) > 0$

Arc	Arc Multiplicity
$Pctneg \rightarrow Tdetect$	$\#(Pctneg)$
$Pcfneg \rightarrow Tdetect$	$\#(Pcfneg)$
$Pctneg \rightarrow Ttndone$	$\max(\#(Pctneg), 1)$
$Pcfneg \rightarrow Tfndone$	$\max(\#(Pcfneg), 1)$
$Pcomp_i \rightarrow Tcdone_i$, for $i \in [1, N/2]$	$\max(\#(Pcomp_i), 1)$
$Pe_i \rightarrow Tfpos$, for $i = 1, 2$	$\#(Pe_i)$
$Pe_i \rightarrow Ttneg$, for $i = 1, 2$	$\#(Pe_i)$

NSCP with Comparison Algorithm

- This model is very similar to the previously discussed NSCP with acceptance test model.
- Initially, there is a single token in both places *Pcompl* and *Pactive*.
- The software block begins operating on the next input immediately with the firing of transition *Tstart*.
- This transition places one token in each of places *Pm1*, *Pm2*, ..., *PmN*, representing the fact that each variant begins operation on the provided input.

NSCP with Comparison Algorithm

- Transitions T_{mi} for $i \in 1, 2, \dots, N$ represents the execution of each variant i .
- As each variant completes execution, a token is placed in $T_{comp} \lceil i/2 \rceil$ (for variant i).
- The self-checking procedure (comparison algorithm execution) is modeled by transition T_{compi} .
- This transition is enabled only when both variants in a pair have completed execution (when two tokens are in place P_{compi}).

NSCP with Comparison Algorithm

- When the comparison test completes, the token is moved from place P_{compi} to place P_{mdonei} (for variant pair i).
- Place P_{active} contains the number of tokens representing the number of the active variant pair (a number between 1 and $N/2$).

NSCP with Comparison Algorithm

- When the active variant pair completes its comparison algorithm, a token is in place P_{mdonei} , enabling transition $T_{activei}$, where i is the number of tokens in place P_{active} .
- The firing of transition $T_{activei}$ moves the token to place P_{avar} .
- This enables transitions $Te1$, $Te2$, and Tne .

NSCP with Comparison Algorithm

- The firing of transition $Te1$ means one of the two variants produced an incorrect output and therefore the comparison test result should be negative.
- The firing of transition $Te2$ means both of the two variants produced an incorrect output and therefore the comparison test result should be negative.
- The firing of transition Tne means neither of the two variants produced an incorrect output and therefore the comparison test result should be positive.

NSCP with Comparison Algorithm

- The firing of transition $Te1$ moves a token to place $Pe1$ and to place $Pmerr$.
- The firing of transition $Te2$ moves a token to place $Pe2$ and two tokens to place $Pmerr$.
- The number of tokens in place $Pmerr$ represents the number of variants that produced an incorrect output on the current dataset.

NSCP with Comparison Algorithm

- A token in place $Pe1$, indicating one of the variant pair produced an incorrect output.
- A token in place $Pe2$ indicates that both of the variants in the pair produced an incorrect output.
- A token in either $Pe1$ or $Pe2$ enables transitions $Tfpos$ and $Ttneg$, which indicate a false positive diagnoses and a true negative diagnoses respectively.

NSCP with Comparison Algorithm

- A false positive diagnosis causes the token to move to place *Pundetect*, indicating an undetected error.
- If a true negative diagnosis is detected, the token is moved to place *Pctneg*.
- Place *Pctneg* counts the number of incorrect variant pair outputs which are diagnosed as true negative.
- The tokens remain in place *Pctneg* until either all variants pairs are diagnosed as incorrect or the active variant pair diagnoses its output to be correct.

NSCP with Comparison Algorithm

- If both variants in the pair produced incorrect output, transition T_{ne} fires, moving the token from place P_{avar} to place P_{ne} .
- The diagnosis of correct output can be either a false negative or a true positive represented by transitions T_{fneg} and T_{tpos} .
- Transition T_{fneg} moves the token from place P_{ne} to place P_{cfneg} .
- Place P_{cfneg} counts the number of correct variant pair outputs diagnosed as false negative.

NSCP with Comparison Algorithm

- The tokens remain in place P_{cfneg} until either all variants are diagnosed as incorrect or the active variant diagnoses its output as correct.
- If the sum of the number of tokens in place P_{ctneg} and P_{cfpos} is equal to $N/2$, all variant pairs have been diagnosed as incorrect.

NSCP with Comparison Algorithm

- This enables transition T_{detect} , which removes all tokens from places P_{ctneg} and P_{cfpos} and places a single token in place P_{detect} ; this represents a detected failure.
- If the diagnosis of the correct output is a true positive, transition T_{tpos} fires, moving the token from place P_{ne} to place P_{compl} .

NSCP with Comparison Algorithm

- A token in place P_{compl} satisfies the guard function for transitions T_{donei} for $i \in [1, N]$, transitions T_{cdonei} and T_{mdonei} for $i \in [1, N/2]$, and transitions T_{tndone} , T_{fndone} , and T_{edone} .
- All tokens in these places are removed from the net, effectively resetting the net to its initial state.
- After this reset, the N self-checking programming block begins execution of the next input.

3. Dependencies in the SRN Models

- **Dependencies** in fault tolerant systems are generally classified according to the **source of the failure**.
- Laprie [Lap90] classified failures in fault tolerant software systems using two criteria:
 - *Separate or common-mode*
 - A *common-mode fault* is a fault which occurs simultaneously in two or more redundant components.
 - *Detected or undetected*

3. Dependencies in The SRN Models

- First, failures are classified as either *separate* or *common-mode*.
- Sources of common-mode failures include
 - *design faults* from shared specification or implementation,
 - *similar errors* from independent faults, and
 - the inherent difficulty of *shared input*.

■ در ادامه تعریف خواهند شد...

- Next, failures can either be *detected* or *undetected*.

3. Dependencies in The SRN Models

- It is most important in the development of a model to account for these dependencies.
- In our SRN models, these dependencies are accounted for
 - by the structure of the model, and
 - by judicious (قابل قضاوت) definition of the immediate transition probabilities.

Detected versus Undetected Failures

- **First, consider the distinction between detected and undetected failures.**
- In the previous section, we developed the SRN model of each software fault tolerance technique which included places P_{detect} , for detected failures, and $P_{undetected}$, for undetected failures.
- Defining separate places for detected and undetected failures, rather a single place (to indicate any type of failure), allows numerical study of several additional measures of interest.

Detected versus Undetected Failures

- **Safety measures include both steady state and transient measures.**
 - A **steady state measure** of interest is the probability the system will eventually fail due to an unsafe failure.
 - An unsafe failure is indicated by the existence of a token in place $P_{undetected}$.
 - A **transient measure** of interest is $S(t)$, the safety distribution, defined to be the probability the system does not enter an unsafe state by time t .

Detected versus Undetected Failures

- **Reliability measures** can be obtained by considering block failure as the existence of a token in either place P_{detect} or $P_{undetected}$.
- **Mean time to failure** is a cumulative measure of the expected time until a token arrives in either place P_{detect} or $P_{undetected}$.
- The **transient reliability function**, $R(t)$, is the probability that there are no tokens in either place P_{detect} or $P_{undetected}$ at time t .

Common-Mode versus Separate Failures

- **Next, consider the distinction between separate and common-mode failures.**
 - **Separate failures** result from independent faults with distinct errors.
 - **Common-mode failures** result from related faults or independent faults subject to similar errors.

Common-Mode versus Separate Failures

- Measurements have shown that software variants do not exhibit separate failures.

□ توضیحی که چرا این طور است نداده و مرجعی هم برای اندازه‌گیری‌های مورد نظر نداده است.

- Measurements provide a **probability mass function** $p_N(\cdot)$ where $p_N(i)$ is the probability that i of the N variants produce incorrect output.
- If all variant failures are separate, then $p_N(\cdot)$ is a **binomial** (دوجمله‌ای) probability mass function.

Common-Mode versus Separate Failures

- Common-mode variant failures can be easily accounted for in the SRN model by carefully structuring the model to retain tokens in places which provide needed information;
 - **state dependent transition probabilities can then be defined to use this information.**

Common-Mode versus Separate Failures

- The state information needed to model common-mode variant failures includes
 - n_{vdone} , the number of variants in the program block which have completed execution, and
 - n_{fail} , the number of the variants which have completed and produced incorrect results.

Common-Mode versus Separate Failures

- In addition, to simplify the probability functions needed in the SRN models, we include in the state information $n_{totfail}$, the number of variants out of N producing incorrect output.
- This variable is computed using probability mass function $p_N(.)$ each time a new dataset begins processing.

Common-Mode versus Separate Failures

- Using the assumption that variants are stochastically identical, we can compute several probabilities of interest in fault tolerant software systems.
- The probability a variant produces incorrect output is given by

$$\text{prob}(\text{variant failure}) = \frac{n_{tot\ fail} - n_{fail}}{N - n_{vdone}}$$

Common-Mode versus Separate Failures

- The probability that less than $N/2$ variants produce incorrect output is given by

$$\text{prob}(\text{no. variants fail} < N/2) = 1_{n_{\text{tot fail}} < N/2}$$

- where 1_x is an **indicator function** which evaluates to 1 if x is *true* and 0 otherwise.

Common-Mode versus Separate Failures

- If we consider a pair of variants, we can compute the probabilities that one, both, or neither of the pair of variants fail.
- The probability both variants produce **correct** output is

$$prob(\text{neither variant fails}) = \left(1.0 - \frac{n_{totfail} - n_{fail}}{N - n_{vdone}}\right) \times \left(1.0 - \frac{n_{totfail} - n_{fail}}{N - (n_{vdone} + 1)}\right)$$

Common-Mode versus Separate Failures

- The probability both variants produce **incorrect** output is

$$prob(\text{both variants fail}) = \frac{n_{totfail} - n_{fail}}{N - n_{vdone}} \times \frac{n_{totfail} - (n_{fail} + 1)}{N - (n_{vdone} + 1)}$$

- The probability that one of the two variants produce incorrect output and the other produces correct output is

$$prob(\text{one of two variants fail}) = 1.0 - (prob(\text{neither variant fails}) + prob(\text{both variants fail}))$$

SRN Models with Common-Mode and Separate Failures

- Figure 6.7 shows a subnet that is added to each previously described SRN model to simplify the incorporation of common-mode failures...

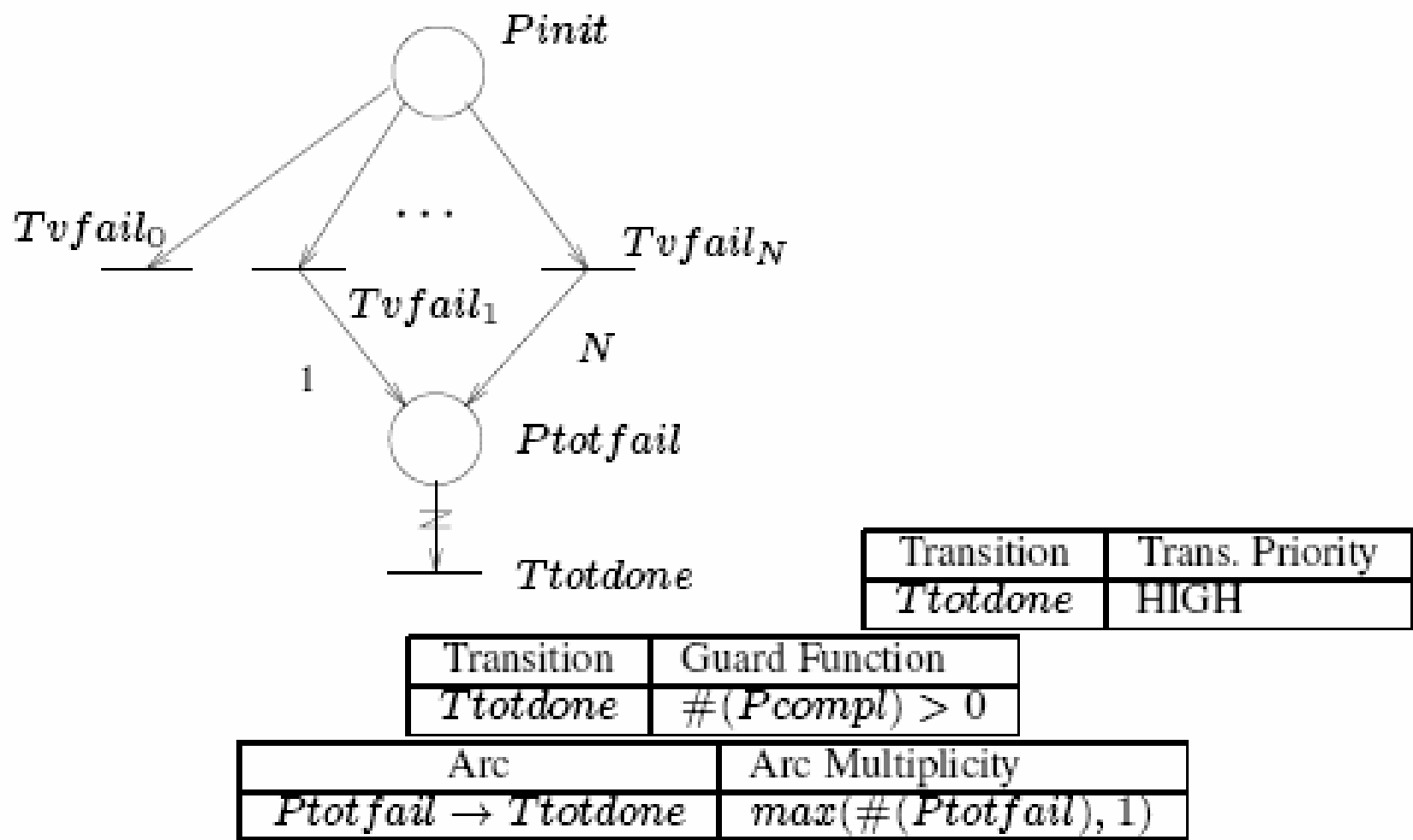


Figure 6.7 Subnet added to SRN models for common-mode failures

SRN Models with Common-Mode and Separate Failures

- A token arrives in transition P_{init} as a result of the firing of transition T_{start} .
- Transition T_{start} (which is part of each previously developed SRN model) is modified to include another output arc associated with place P_{init} .
- When a token arrives in place P_{init} , the software block is ready to operate on a new dataset.
- Transitions T_{vfail_0} , T_{vfail_1} , ... T_{vfail_N} become enabled.

SRN Models with Common-Mode and Separate Failures

- The probability associated with each transition T_{vfail_i} is $p_N(i)$, the probability that i out of the N variants produce an incorrect result.
- The firing of transition T_{vfail_i} causes i tokens to be placed in $P_{totfail}$.
- Place $P_{totfail}$ represents the number of variants that will produce incorrect output on the current dataset.
- The number of tokens in place $P_{totfail}$ is used to determine the variant failure probabilities in each SRN model.

SRN Models with Common-Mode and Separate Failures

- This is discussed in detail for each SRN model in the next section.
- When the software block completes execution on the current dataset (a token is moved to place P_{compl}), all tokens in place $P_{totfail}$ are removed by the firing of transition $T_{totdone}$.
- This resets this subnet prior to the arrival of the next dataset.

Recovery Block SRN Model

- In the SRN model of the RB scheme, transitions T_{nei} and T_{ei} are immediate transitions representing the correctness or incorrectness of variant i .
- These transitions are enabled only after $i-1$ variants have completed execution.
- Of these $i-1$ variants, $\#(P_{mfail})$ produced incorrect results.

Recovery Block SRN Model

- The immediate transition probabilities for T_{ei} and T_{nei} incorporating common-mode failures are given by

$$\begin{aligned} \text{prob}(T_{ei}) &= \frac{n_{totfail} - n_{fail}}{N - n_{udone}} \\ &= \frac{\#(P_{totfail}) - \#(P_{mfail})}{N - (i - 1)} \end{aligned}$$

and

$$\text{prob}(T_{nei}) = 1 - \text{prob}(T_{ei})$$

NVP SRN Model

- In the SRN model of the NVP scheme, out of the N available variants $\#(P_{totfail})$ variants produce incorrect results.
- The voter diagnosis is dependent on the number of the N variants producing incorrect output.
- If less than half of the variants produce correct output (that is if $\#(P_{totfail}) < N/2$), then the vote should be positive.
- However, similar errors may cause the voter to diagnose a false positive when less than half of the variants produce a correct output.

NVP SRN Model

- In addition, the implementation of the voter may be incorrect (e.g. the voter's variant error tolerance may be too small) and the voter may diagnose a false negative even though more than half of the variants produced a correct output.

NVP SRN Model

$$\begin{aligned} \text{prob}(T fpos) &= \text{prob}(\text{at least half of variants were incorrect}) \times \\ &\quad \text{prob}(\text{diagnosis on incorrect input is positive}) \\ \text{prob}(T tneg) &= \text{prob}(\text{at least half of variants were incorrect}) \times \\ &\quad (1.0 - \text{prob}(\text{diagnosis on incorrect input is positive})) \\ \text{prob}(T fneg) &= \text{prob}(\text{less than half of variants were incorrect}) \times \\ &\quad \text{prob}(\text{diagnosis on correct input is negative}) \\ \text{prob}(T tpos) &= \text{prob}(\text{less than half of variants were incorrect}) \times \\ &\quad (1.0 - \text{prob}(\text{diagnosis on correct input is negative})) \end{aligned}$$

NVP SRN Model

- The variant probabilities used in the above equations are given by

$$prob(\text{at least half of variants are incorrect}) = 1_{\#(P_{totfail}) \geq N/2}$$

$$prob(\text{less than half of variants are incorrect}) = 1_{\#(P_{totfail}) < N/2}$$

NSCP with AT SRN Model

- In the SRN model of the NSCP with acceptance test, a token in place P_{avar} enables transitions T_e , which indicates an incorrect variant result, and transition T_{ne} , which indicates a correct variant result.
- The number of previously completed and diagnosed variants is $\#(P_{ctneg}) + \#(P_{cfneg})$.
- The number of these variants which produced incorrect results is $\#(P_{ctneg})$.

NSCP with AT SRN Model

- The probability that the variant represented by a token in place P_{avar} produces an incorrect result is

$$\begin{aligned} \text{prob}(Te) &= \frac{n_{totfail} - n_{fail}}{N - n_{vdone}} \\ &= \frac{\#(P_{totfail}) - \#(P_{ctneg})}{N - (\#(P_{ctneg}) + \#(P_{cfneg}))} \end{aligned}$$

and

$$\text{prob}(Tne) = 1 - \text{prob}(Te)$$

NSCP with Comparison SRN Model

- Similarly, in the SRN model of the NSCP with comparison tests, a token in place *Pavar* enables transitions *Te1*, *Te2*, and *Tne*.
- The firing of transition *Te1* indicates that one variant in the pair produced an incorrect output while the other variant produced a correct output.
- The firing of transition *Te2* indicates that both variants in the pair produced incorrect output.
- The firing of transition *Tne* indicates that both of the variants in the pair produced correct output.

NSCP with Comparison SRN Model

- The number of variant pairs that have completed execution and diagnosis is given by $\#(Pctneg)+\#(Pcfneg)$;
 - the number of variants that have completed execution is therefore $2\times(\#(Pctneg)+\#(Pcfpos))$.
- Of the variant pairs that have completed, the number of pairs where at least one variant did not produce correct output is given by $\#(Pmerr)$.

NSCP with Comparison SRN Model

- The probability neither variant produces incorrect output is

$$\begin{aligned} \text{prob}(Tne) &= \left(1.0 - \frac{n_{totfail} - n_{fail}}{N - n_{vdone}} \right) \times \left(1.0 - \frac{n_{totfail} - n_{fail}}{N - (n_{vdone} + 1)} \right) \\ &= \left(1.0 - \frac{\#(P_{totfail}) - \#(P_{merr})}{N - 2 \times (\#(P_{ctneg}) + \#(P_{cfneg}))} \right) \times \\ &\quad \left(1.0 - \frac{\#(P_{totfail}) - \#(P_{merr})}{N - 2 \times (\#(P_{ctneg}) + \#(P_{cfneg})) - 1} \right) \end{aligned}$$

NSCP with Comparison SRN Model

- The probability both variants produce incorrect output is

$$\begin{aligned} \text{prob}(Te2) &= \frac{n_{totfail} - n_{fail}}{N - n_{vdone}} \times \frac{n_{totfail} - (n_{fail} + 1)}{N - (n_{vdone} + 1)} \\ &= \frac{\#(P_{totfail}) - \#(P_{merr})}{N - 2 \times (\#(P_{ctneg}) + \#(P_{cfneg}))} \times \\ &\quad \frac{\#(P_{totfail}) - \#(P_{merr}) - 1}{N - 2 \times (\#(P_{ctneg}) + \#(P_{cfneg})) - 1} \end{aligned}$$

NSCP with Comparison SRN Model

- The probability that one of the two variants produce incorrect output and the other produces correct output is

$$\text{prob}(Te1) = 1.0 - \text{prob}(Tne) - \text{prob}(Te2)$$