

In the name of God

2. Complexity Theory

2.2. Complexity of Problems

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Easy vs. Difficult Problems

- **Tractable or Easy Problems**

- The problems that are solvable by **polynomial-time algorithms** are **tractable**, or **easy**

- **Intractable or Difficult Problems**

- The problems that require **super-polynomial time** are **intractable**, or **hard**.

Decision & Optimization Problems

- **Decision Problems**

- Given an input and a question regarding a problem, determine if the answer is **yes** or **no**

- **Example: Prime number decision problem.**

- Is a given number Q a prime number?
- It will return *yes* if the number Q is a prime one, otherwise the *no* answer is returned.

Decision & Optimization Problems

- **Optimization Problems**

- Find a solution with the “best” value

- **Example: Traveling Salesman Problem.**

- “find the optimal Hamiltonian tour that optimizes the total distance,”

Decision & Optimization Problems

- An optimization problem can always be reduced to a decision problem.
- **Example: Optimization versus decision problem.**
 - The TSP can be reduced to a decision problem: “given an integer D , is there a Hamiltonian tour with a distance less than or equal to D ?”

Class P Problems

- **Class P Problems**

- The family of problems where a known deterministic polynomial-time algorithm exists to solve the problem.
- They can be solved in time $O(n^k)$ for some constant k , where n is the size of the input to the problem.

Class P Problems

- **Some problems of class P**
 - linear programming
 - shortest path problems
 - maximum flow network
 - minimum spanning tree

Nondeterministic Polynomial Algorithms

- Nondeterministic algorithm = two stage procedure:
- 1) Nondeterministic (“guessing”) stage:
 - generate randomly an arbitrary string that can be thought of as a candidate solution (“certificate”)
- 2) Deterministic (“verification”) stage:
 - take the certificate and the instance to the problem and returns YES if the certificate represents a solution
- **NP algorithms (Nondeterministic polynomial)**
 - verification stage is polynomial

Nondeterministic Polynomial Algorithms

- **Example: Nondeterministic algorithm for the 0–1 knapsack problem.**
 - The 0–1 knapsack decision problem:
 - ◆ Given a set of N objects.
 - ◆ Each object O has a specified weight and a specified value.
 - ◆ Given a capacity, which is the maximum total weight of the knapsack, and a quota, which is the minimum total value that one wants to get.
 - ◆ The 0–1 knapsack decision problem consists in finding a subset of the objects whose **total weight** is at most **equal to the capacity** and whose total value is **at least equal** to the specified **quota**.

Nondeterministic Polynomial Algorithms

- Nondeterministic algorithm for the knapsack problem

Input OS : set of objects ; QUOTA : number ; CAPACITY : number.

Output S : set of objects ; FOUND : boolean.

S = empty ; total_value = 0 ; total_weight = 0 ; FOUND = false ;

Pick an order L over the objects ;

Loop

Choose an object O in L ; Add O to S ;

total_value = total_value + O.value ;

total_weight = total_weight + O.weight ;

If total_weight > CAPACITY **Then** fail

Else If total_value ≥ QUOTA

FOUND = true ;

succeed ;

Endif Endif

Delete all objects up to O from L ;

Endloop

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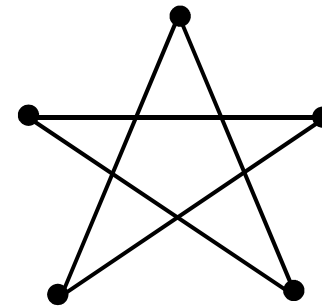
Class NP Problems

- **Class NP Problems**

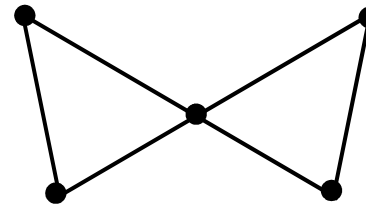
- NP problems stands for **Nondeterministic Polynomial-time Problems**
- The set of all decision problems that can be solved by a **nondeterministic algorithm**.
 - ◆ i.e., verifiable in polynomial time
- If we were somehow given a solution, then we could verify that the solution is correct in time polynomial in the size of the input to the problem.
- **Common error:** NP does **not** mean “**non-polynomial**”

Example: Hamiltonian Cycle

- **Given:** a directed graph $G = (V, E)$, determine a simple cycle that contains each vertex in V
 - Each vertex can only be visited once
- **Certificate:**
 - Sequence: $\langle v_1, v_2, v_3, \dots, v_{|V|} \rangle$



hamiltonian

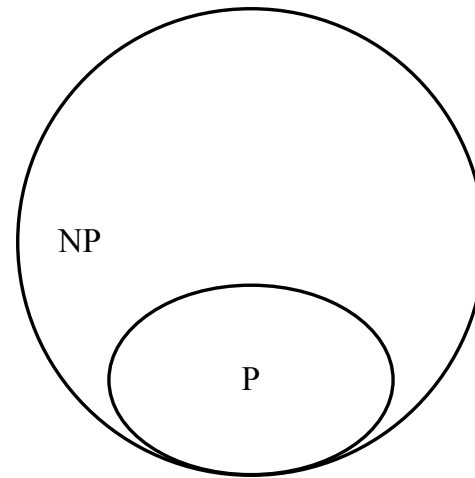


not
hamiltonian

Is $P = NP$?

- Any problem in P is also in NP :

$$P \subseteq NP$$

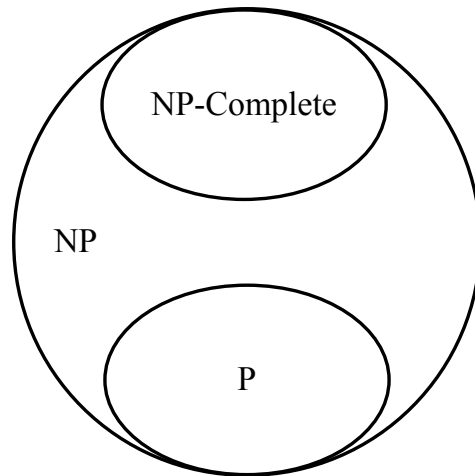


- Obviously, for each problem in P we have a nondeterministic algorithm solving it.

Class NP-Complete Problems

- **Class NP-Complete Problems**

- NP-Complete problems stands for **Nondeterministic Polynomial-time Complete Problems**
- The NP-complete problems are the hardest problems in NP
- The problems that no one can solve them in a polynomial-time



P & NP-Complete Problems

- **Shortest simple path**

- Given a graph $G = (V, E)$ find a **shortest** path from a source to all other vertices
- Polynomial solution: $O(VE)$

- **Longest simple path**

- Given a graph $G = (V, E)$ find a **longest** path from a source to all other vertices
- NP-complete

P & NP-Complete Problems

- **Euler tour**

- $G = (V, E)$ a connected, directed graph find a cycle that traverses each edge of G exactly once (may visit a vertex multiple times)
- Polynomial solution $O(E)$

- **Hamiltonian cycle**

- $G = (V, E)$ a connected, directed graph find a cycle that visits each vertex of G exactly once
- NP-complete

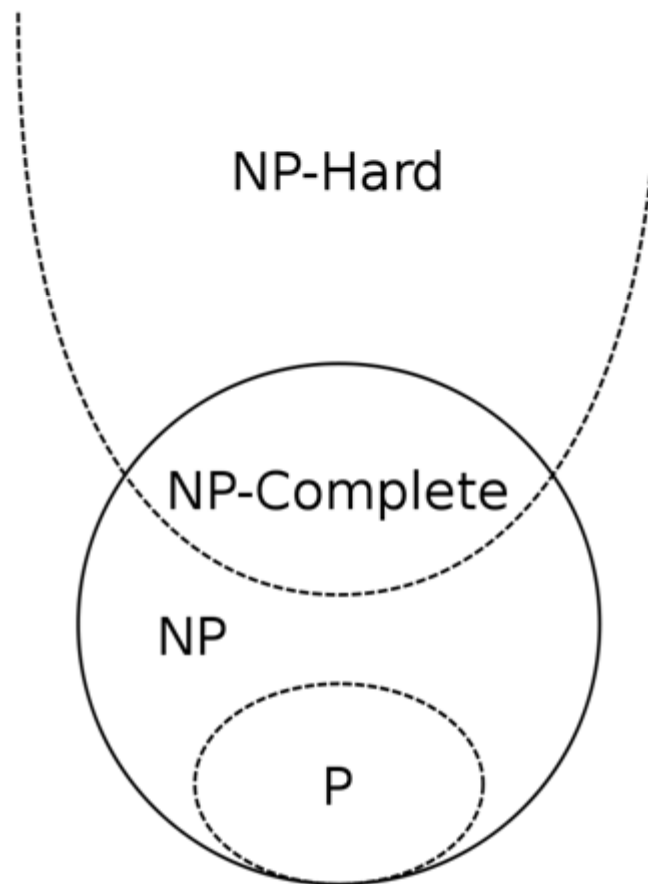
NP-Hard Problems

- **NP-Hard problems**

- NP-hard stands for **Nondeterministic Polynomial-time Hard**
- Most of the real-world optimization problems are NP-hard for which provably efficient algorithms do not exist.
- They require **exponential time** to be solved in optimality.
- Metaheuristics constitute an important alternative to solve this class of problems.
- NP-hard problems may be of any type: decision problems, search problems, or optimization problems.

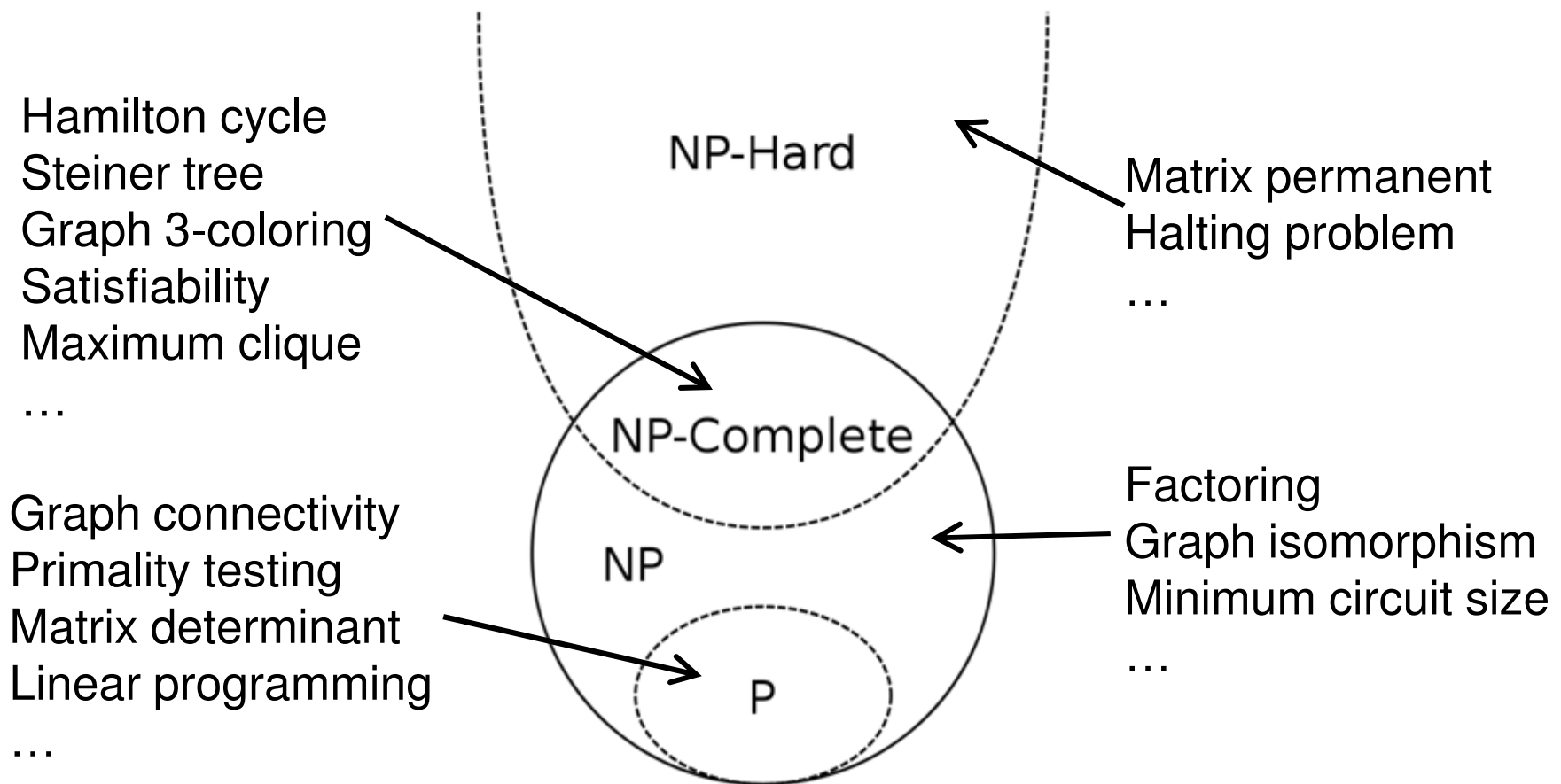
NP-Hard Problems

- NP-hard problems do not necessarily belong to NP.
- An NP-hard problem that is in NP is said to be NP-complete.



NP-Hard Problems

- Some examples



Some NP-hard problems

- Sequencing and scheduling problems
 - such as flow-shop scheduling, job-shop scheduling, or open-shop scheduling.
- Assignment and location problems
 - such as quadratic assignment problem (QAP), generalized assignment problem (GAP), location facility, and the p-median problem.
- Grouping problems
 - such as data clustering, graph partitioning, and graph coloring.
- Routing and covering problems
 - such as vehicle routing problems (VRP), set covering problem (SCP), Steiner tree problem, and covering tour problem (CTP).
- Knapsack and packing/cutting problems, and so on.

NP-hard Problems

- Integer programming models belong in general to the NP-hard class.
- Unlike LP models, IP problems are difficult to solve because the feasible region is not a convex set.

Relation among P, NP, NPC, NP-Hard

- $P \subseteq NP$
- $NP\text{-Complete} \subseteq NP$
- $NP\text{-Complete} \subset NP\text{-Hard}$

Complexity of Problems

- To become a good algorithm designer, you must understand the basics of the theory of NP-completeness.
- If you can establish a problem as NP-hard, you provide good evidence for its intractability.
- As an engineer, you would then do better spending your time developing an approximation algorithm, rather than searching for a fast algorithm that solves the problem exactly.
- Thus, it is important to become familiar with this remarkable class of problems.

References

References

- Thomas H. Cormen et al., **Introduction to Algorithms**, Second Edition, The MIT Press, 2001.
(Chapter 34)
- El-Ghazali Talbi, **Metaheuristics : From Design to Implementation**, John Wiley & Sons, 2009.
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