

**In the name of God**

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# **Network Flows**

## **3. Shortest Path Problems**

### **3.1 Introduction**

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# Shortest Path Problems

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- *Shortest path problems* are attractive to both researchers and to practitioners for several reasons:
  - (1) they arise frequently in practice
  - (2) they are easy to solve efficiently
  - (3) they provide both a benchmark and a point of departure for studying more complex network models
  - (4) they arise frequently as subproblems when solving many combinatorial and network optimization problems

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# **Notation and Assumptions**

# Notation and Assumptions

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- *Notation and Assumptions*

- $G = (N, A)$  : a directed network with an arc length (or arc cost)  $c_{ij}$  associated with each arc  $(i, j) \in A$ .
- $s$  : the source.
- $A(i)$  : represent the arc adjacency list of node  $I$
- $C = \max\{c_{ij} : (i, j) \in A\}$ .
- *the length of a directed path* : the sum of the lengths of arcs in the path.

# Notation and Assumptions

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- The *shortest path problem*
  - is to determine for every non source node  $i \in N$  a shortest length directed path from node  $s$  to node  $i$ .
- Alternatively,
  - the problem as sending 1 unit of flow as cheaply as possible (with arc flow costs as  $c_{ij}$ ) from node  $s$  to each of the nodes in  $N - \{s\}$  in an **uncapacitated network**.
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# Notation and Assumptions

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- *The linear programming formulation of the shortest path problem:*

$$\text{Minimize } \sum_{(i,j) \in A} c_{ij} x_{ij}$$

subject to

$$\sum_{\{j:(i,j) \in A\}} x_{ij} - \sum_{\{j:(j,i) \in A\}} x_{ji} = \begin{cases} n - 1 & \text{for } i = s \\ -1 & \text{for all } i \in N - \{s\} \end{cases}$$

$$x_{ij} \geq 0 \quad \text{for all } (i, j) \in A.$$

# Notation and Assumptions

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- *Assumption 1. All arc lengths are integers*
  - The integrality assumption imposed on arc lengths is necessary for some algorithms and unnecessary for others.
  - We can always transform rational arc capacities to integer arc capacities by multiplying them by a suitably large number.
  - Therefore, the integrality assumption is really not a restrictive assumption in practice.

# Notation and Assumptions

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- *Assumption 2. The network contains a directed path from node  $s$  to every other node in the network.*
  - We can always satisfy this assumption by adding a *fictitious* arc  $(s, i)$  of suitably large cost for each node  $i$  that is not connected to node  $s$  by a directed path.



# Notation and Assumptions

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- *Assumption 3. The network does not contain a negative cycle (i.e., a directed cycle of negative length).*
  - For any network containing a negative cycle  $W$ , the linear programming formulation has an unbounded solution because we can send an infinite amount of flow along  $W$ .
  - The shortest path problem with a negative cycle is an **NP-complete** problem, no polynomial-time algorithm for this problem is likely to exist

# Notation and Assumptions

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- *Assumption 4.4. The network is directed.*
  - If the network were undirected and all arc lengths were nonnegative, we could transform this shortest path problem to one on a directed network.

# Various Types of Shortest Path Problems

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- *Various Types of Shortest Path Problems*
  - *the single-source shortest path problem*
    - ◆ Finding shortest paths from one node to all other nodes
  - *the all-pairs shortest path problem*
    - ◆ Finding shortest paths from every node to every other node

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# **Algorithmic approaches for solving shortest path problems**

# Label-Setting and Label-Correcting Algorithms

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- Algorithmic approaches for solving shortest path problems:
  - *label setting algorithms*
  - *label correcting algorithms*
- *Characteristics:*
  - Both approaches are iterative.
  - They assign tentative *distance labels* to nodes at each step
  - The distance labels are estimates of (i.e., upper bounds on) the shortest path distances.
  - The approaches vary in how they update the distance labels from step to step and how they *converge* toward the shortest path distances.

# Label-Setting and Label-Correcting Algorithms

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- *Updating the distance labels*
  - Label-setting algorithms designate one label as permanent (optimal) at each iteration.
  - Label-correcting algorithms consider all labels as temporary until the final step, when they all become permanent.

# Label-Setting and Label-Correcting Algorithms

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- *The class of problems that they solve*
  - Label-setting algorithms are applicable only to
    - ◆ (1) shortest path problems defined on acyclic networks with arbitrary arc lengths, and to
    - ◆ (2) shortest path problems with nonnegative arc lengths.
  - The label-correcting algorithms
    - ◆ are more general and apply to all classes of problems, including those with negative arc lengths.

# Label-Setting and Label-Correcting Algorithms

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- *Efficiency of the approaches*
  - The label-setting algorithms are much more efficient, that is, have much better worst-case complexity bounds;
  - The label-correcting algorithms not only apply to more general classes of problems, but as we will see, they also offer more algorithmic flexibility.
- In fact, we can view the label-setting algorithms as special cases of the label-correcting algorithms.



# Shortest Path Tree

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- In the shortest path problem, we wish to determine a shortest path from the source node to all other  $(n - 1)$  nodes.
- How much storage would we need to store these paths?
  - One naive answer would be an upper bound of  $(n - 1)^2$  since each path could contain at most  $(n - 1)$  arcs.
- We need not use this much storage:  $(n - 1)$  storage locations are sufficient to represent all these paths.

# Shortest Path Tree

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- ***Shortest path tree***

- We can always find a ***directed out-tree rooted*** from the source with the property that the unique path from the source to any node is a shortest path to that node.
- We refer to such a tree as a ***shortest path tree***.

- The shortest path tree relies on the following property.
  - **If the path  $s = i_1 - i_2 - \dots - i_h = k$  is a shortest path from node  $s$  to node  $k$ , then for every  $q = 2, 3, \dots, h - 1$ , the subpath  $s = i_1 - i_2 - \dots - i_q$  is a shortest path from the source node to node  $i_q$ .**



The End