In the name of God

Network Flows

3. Shortest Path Problems3.2 Dijkstra's Algorithm

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- finds shortest paths from the source node *s* to all other nodes in a network with *nonnegative arc lengths*.
- It is a *label setting algorithm*
- Dijkstra's algorithm maintains a distance label *d*(*i*) with each node *i*, which is an upper bound on the shortest path length to node *i*.
- At any intermediate step, the algorithm divides the nodes into two groups:
 - those which it designates as *permanently labeled* (or permanent)
 - those it designates as *temporarily labeled* (or temporary).

- The distance label
 - to any permanent node represents the shortest distance from the source to that node.
 - to any temporary node represents an upper bound on the shortest path distance to that node.
- The basic idea of the algorithm is to fan out from node *s* and permanently label nodes in the order of their distances from node *s*.
- Initially, we give node s a permanent label of zero, and each other node *j* a temporary label equal to ∞.

- At each iteration, the label of a node *i* is its shortest distance from the source node along a path whose internal nodes (i.e., nodes other than *s* or the node *i* itself) are all permanently labeled.
- The algorithm selects a node *i* with the minimum temporary label (breaking ties arbitrarily), makes it permanent, and reaches out from that node-that is, scans arcs in *A*(*i*) to update the distance labels of adjacent nodes.
- The algorithm terminates when it has designated all nodes as permanent.

- Dijkstra's algorithm maintains a *directed out-tree T* rooted at the source that spans the nodes with finite distance labels.
- The algorithm maintains this tree using predecessor indices [i.e., if (*i*, *j*) ∈ *T*, then *pred*(*j*) = *i*].
- The algorithm maintains the invariant property that every tree arc (i, j) satisfies the condition $d(j) = d(i) + c_{ij}$
- with respect to the current distance labels.
- At termination, when distance labels represent shortest path distances, *T* is a *shortest path tree*.

• Let

- $d^*(j)$: denote the shortest path distance from node *s* to node *j*.
- *S* : denotes the set of *permanently labeled nodes*.
 - That is, $d(j) = d^*(j)$ for $j \in S$.
- \overline{S} : denotes the set of **temporarily labeled nodes**.
 - That is, $d(j) \ge d^*(j)$ for $j \in T$.
- Dijkstra'salgorithm will determine $d^*(j)$ for each *j*, in order of increasing distance from the origin node 1.

algorithm Dijkstra; begin $S := \emptyset; \overline{S} := N;$ $d(i) := \infty$ for each node $i \in N$; d(s) := 0 and pred(s) := 0; while |S| < n do begin let $i \in \overline{S}$ be a node for which $d(i) = \min\{d(j) : j \in \overline{S}\}$; $S:=S\cup\{i\};$ $\overline{S}:=\overline{S}-\{i\};$ for each $(i, j) \in A(i)$ do if $d(j) > d(i) + c_{ij}$ then $d(j) := d(i) + c_{ij}$ and pred(j) := i; end; end;







- The bottleneck of *Dijkstra's algorithm* is node selection.
 - Scanning all temporarily labeled nodes at each iteration to find the one with the minimum distance label, takes high computation time
- Dial's algorithm
 - tries to maintain distances in some sorted fashion and reduces the algorithm's computation time in practice

• Dial's algorithm

- stores nodes with finite temporary labels in a sorted fashion.
- It maintains nC + 1 sets, called *buckets*, numbered 0,1,2, . . . , nC:
- Bucket k stores all nodes with temporary distance label equal to k.
- *C* : represents the largest arc length in the network, and therefore *nC* is an upper bound on the distance label of any finitely labeled node .
- We need not store nodes with infinite temporary distance labels in any of the buckets-we can add them to a bucket when they first receive a finite distance label.

• We represent the content of bucket *k* by the set *content*(*k*).

- In the node selection operation:
 - we scan buckets numbered 0, 1, 2, ..., until we identify the first *nonempty bucket*.
 - Suppose that bucket *k* is the first nonempty bucket.
 - Then each node in *content*(k) has the minimum distance label.
 - One by one, we delete these nodes from the bucket, designate them as permanently labeled, and scan their arc lists to update the distance labels of adjacent nodes.
 - Whenever we update the distance label of a node *i* from d_1 to d_2 ; we move node *i* from $content(d_1)$ to $content(d_2)$.

- In the next node selection operation, we resume the scanning of buckets numbered k + 1, k + 2, ... to select the next nonempty bucket.
- Property 4.5 implies that the buckets numbered 0, 1, 2, ..., k will always be empty in the subsequent iterations and the algorithm need not examine them again.

The End