In the name of God

# **Network Flows**

# 7. Multicommodity Flows Problems7.2 Lagrangian Relaxation Approach

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• The multicommodity flow problem formulation:

Minimize  $\sum_{1 \le k \le K} c^k x^k$ 

subject to

 $\sum_{1 \le k \le K} x_{ij}^k \le u_{ij} \quad \text{for all } (i, j) \in A,$  $\mathcal{N} x^k = b^k \quad \text{for } k = 1, 2, \dots, K,$  $0 \le x_{ij}^k \le u_{ij}^k \quad \text{for all } (i, j) \in A \text{ and all } k = 1, 2, \dots, K.$ 

• We associate nonnegative Lagrange multipliers  $w_{ij}$  with the bundle constraints, creating the following *Lagrangian subproblem*:

$$L(w) = \min \sum_{1 \le k \le K} c^k x^k + \sum_{(i,j) \in A} w_{ij} (\sum_{1 \le k \le K} x_{ij}^k - u_{ij})$$

• or, equivalently,

$$L(w) = \min \sum_{1 \le k \le K} \sum_{(i,j) \in A} (c_{ij}^{k} + w_{ij}) x_{ij}^{k} - \sum_{(i,j) \in A} w_{ij} u_{ij}$$

• subject to

 $\mathcal{N}x^{k} = b^{k} \quad \text{for all } k = 1, \dots, K,$  $x_{ij}^{k} \ge 0 \quad \text{for all } (i, j) \in A \text{ and all } k = 1, 2, \dots, K.$ 

• Since the term

$$-\sum_{(i,j)\in A} w_{ij}u_{ij}$$

• is a constant for any given choice of the Lagrange multipliers therefore we can ignore it.

- The resulting objective function has a cost  $c_{ij}^{k} + w_{ij}$
- associated with every flow variable  $x_{ij}^k$

- Since none of the constraints in this problem contains the flow variables for more than one of the commodities,
  - the problem decomposes into separate minimum cost flow problems, one for each commodity.
- Consequently, to apply the subgradient optimization procedure to this problem, we would alternately
  - (1) solve a set of minimum cost flow problems (for a fixed value of the Lagrange multipliers w) with the cost coefficients  $c_{ij}^{k/2} + w_{ij}$
  - (2) update the multipliers by the algorithmic procedures

• If  $y_{ij}^k$  denotes the optimal solution to the minimum cost flow subproblems when the Lagrange multipliers have the value  $w_{ij}^q$  at the *q*th iteration, the subgradient update formula becomes:

$$w_{ij}^{q+1} = [w_{ij}^{q} + \theta_q (\sum_{1 \le k \le K} y_{ij}^{k} - u_{ij})]^+$$

- In this expression, the notation  $[\alpha]^+$  denotes the positive part of  $\alpha$ , that is, max $(\alpha, 0)$ .
- The scalar  $\theta_q$  is a step size specifying how far we move from the current solution  $w_{ij}^q$

• If the subproblem solutions  $y_{ij}^k$  use more than the available capacity  $u_{ij}$  of that arc, the update formula increases the multiplier  $w_{ij}^q$  on arc (i, j) by the amount:

$$\left(\sum_{1\leq k\leq K}y_{ij}^k-u_{ij}\right)$$

• If the subproblem solutions  $y_{ij}^k$  use less than the available capacity of that arc, the update formula reduces the Lagrange multiplier of arc (i, j) by the amount:

$$(u_{ij} - \sum_{1 \leq k \leq K} y_{ij}^k)$$

- The decrease would cause the multiplier  $w_{ij}^{q+1}$  to become negative, we reduce the multiplier to value zero.
- We choose the step sizes  $\theta_q$  for iterations q = 1, 2, ..., in accordance with:

$$\theta_k = \frac{\lambda_k [UB - L(\mu^k)]}{\|\mathscr{A}x^k - b\|^2}.$$

• Whenever we apply Lagrangian relaxation to any linear program, such as the multicommodity flow problem, the optimal value

$$L^* = \max_{w \ge 0} L(w)$$

• of the Lagrangian multiplier problem equals the optimal objective function value *z*\* of the linear program.

• Example:

- Consider a two-commodity problem



- For any choice of the Lagrange multipliers  $w_{l2}$  and  $W_{s^1t^1}$  for the two capacitated arcs (s<sup>1</sup>, t<sup>1</sup>) and (1, 2), the problem decomposes into two shortest path problems.
- If we start with the Lagrange multipliers  $w_{12}^0 = w_{s_1t_1}^0 = 0$

• then in the subproblem solutions, the shortest path:

- the shortest path  $s^1$ - $t^1$  carries 10 units of flow at a cost of 1(10) = 10 and,
- the shortest path  $s^2-1-2-t^2$  carries 20 units of flow at a cost of 3(20) = 60
- Therefore, L(0) = 10 + 60 = 70 is a lower bound on the optimal objective function value for the problem.

• Since

$$y_{s_{1t_{1}}}^{1} + y_{s_{1t_{1}}}^{2} - u_{s_{1t_{1}}} = 5$$
  
$$y_{12}^{1} + y_{12}^{2} - u_{12} = 10$$

• The update formulas become:

$$w_{ij}^{q+1} = [w_{ij}^{q} + \theta_{q} (\sum_{1 \le k \le K} y_{ij}^{k} - u_{ij})]^{+}$$
$$w_{s_{1t}^{1}}^{1} = [0 + \theta_{0} \cdot 5]^{+}$$
$$w_{12}^{1} = [0 + \theta_{0} \cdot 10]^{+}$$

• If we choose 
$$\theta_0 = 1$$
, then  
 $w_{s^1t^1}^1 = 5$  and  $w_{12}^1 = 10$ .

• The new shortest path solutions send:

- 10 units on the path  $s^{1}-t^{1}$  at a cost of (1 + 5) (10) = 60
- 20 units on the path  $s^2 t^2$  at a cost of 5(20) = 100

• The new lower bound obtained through:

$$L(w) = \min \sum_{1 \le k \le K} \sum_{(i,j) \in A} (c_{ij}^{k} + w_{ij}) x_{ij}^{k} - \sum_{(i,j) \in A} w_{ij} u_{ij}$$
  
60 + 100 -  $w_{12}^{1} u_{12} - w_{s_{1t}}^{1} u_{s_{1t}}^{1} =$   
160 - 10(10) - 5(5) = 35

• The value of the lower bound has decreased.

• At this point:  $y_{s^{1}t^{1}}^{1} + y_{s^{1}t^{1}}^{2} - u_{s^{1}t^{1}} = 5$  $y_{12}^1 + y_{12}^2 - u_{12} = -10$ • so the update formulas become  $w_{ii}^{q+1} = [w_{ii}^{q} + \theta_{q} (\sum y_{ii}^{k} - u_{ij})]^{+}$  $1 \leq k \leq K$  $w_{s^{1}t^{1}}^{1} = [5 + \theta_{0} \cdot 5]^{+}$  $w_{12}^1 = [10 - \theta_0 \cdot 10]^+$ • If we choose  $\theta_0 = 1$ ,  $w_{s^{1}t^{1}}^{1} = 10$  $w_{12}^1 = 0$ 

• The new shortest path solutions send:

- 10 units on the path  $s^{1}-t^{1}$  at a cost of (1 + 10) (10) = 110 and
- 20 units on the path  $s^2-1-2-t^2$  at a cost of 3(20) = 60
- If we continue by choosing the step sizes for the *k*th iteration as  $\theta_k = 1/k$ , we obtain the set of iterates:

Iteration number q	<i>w</i> <sup><i>q</i></sup> <sub>12</sub>	$W_s^{q_{l_t}1}$	Shortest paths	Shortest path costs	$\frac{10w_{12}^q}{+ 5w_{s_1t_1}^{q_1}}$	Lower bound L(w <sup>q</sup> )	θq
0	0	0	$s^{1}-t^{1}$ $s^{2}-1-2-t^{2}$	$10(1) \\ 20(1 + 1 + 1)$	0	70	1
1	10	5	$s^1 - t^1$ $s^2 - t^2$	10(1 + 5) 20(5)	125	. 35	1
2	0	10	$s^{1}-t^{1}$ $s^{2}-1-2-t^{2}$	$   \begin{array}{r}     10(1 + 10) \\     20(1 + 1 + 1)   \end{array} $	50	120	0.5
3	5	12.5	$s^1 - t^1$ $s^2 - t^2$	10(1 + 12.5) 20(5)	112.5	122.5	0.333
4	1.67	14.17	$s^{1}-1-2-t^{1}$ $s^{2}-1-2-t^{2}$	$\begin{array}{r} 10(5 + 2.67 + 5) \\ 20(1 + 2.67 + 1) \end{array}$	87.55	132.5	0.25
5	6.67	12.92	$\frac{s^1 - t^1}{s^2 - t^2}$	10(1 + 12.92) 20(5)	131.3	107.9	0.2
6	4.67	13.92	$s^{1}-t^{1}$ $s^{2}-t^{2}$	10(1 + 13.92) 20(5)	116.3	132.9	0.167
7	3	14.75	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 4 + 5)}{20(5)}$	103.8	136.3	0.143

Iteration number q	w <sub>12</sub> <sup>q</sup>	$W_s^{q_1}t^1$	Shortest paths	Shortest path costs	$\frac{10w_{12}^q}{+ 5w_{s_1t_1}^{q_1}}$	Lower bound $L(w^q)$	$\theta_q$
8	3	14.04	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 4 + 5)}{20(5)}$	100.2	139.8	0.125
9	3	13.41	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 4 + 5)}{20(5)}$	97.05	143.0	0.111
10	3	12.86	$s^1 - t^1$ $s^2 - t^2$	10(1 + 12.86) 20(5)	94.3	144.3	0.1
11	2	13.36	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 3 + 5)}{20(5)}$	86.8	143.2	0.091
12	2	12.9	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 3 + 5)}{20(5)}$	84.5	145.5	0.083
13	2	12.48	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 3 + 5)}{20(5)}$	82.2	147.6	0.077
14	2	12.09	$s^{1}-1-2-t^{1}$ $s^{2}-t^{2}$	$\frac{10(5 + 3 + 5)}{20(5)}$	80.25	149.5	0.071

• From iteration 14 on, the values of the Lagrange multipliers oscillate about, and converge to, their optimal values:

$$w_{12} = 2$$
  
 $w_{s^1t^1} = 12$ 

• The optimal lower bound oscillates about its optimal value 150, which equals the optimal objective function value of the multicommodity flow problem.

• This figure shows how the values of the Lagrange multipliers vary during the execution of the algorithm



• This figure shows how the values of Lagrangian lower bounds vary during the execution of the algorithm



- Advantages of subgradient optimization for solving the Lagrangian multiplier problem:
  - (1) This solution approach permits us to exploit the underlying network flow structure.
  - (2) The formulas for updating the Lagrange multipliers  $w_{ij}$  are rather small computationally and very easy to encode in a computer program.

#### • Limitations of subgradient optimization:

- (1) To ensure convergence we need to take small step sizes;
   as a result, the method does not converge very fast.
- (2) the optimal flows  $y_{ij}^k$  solve the Lagrangian subproblem, these subproblems might also have other optimal solutions that do not satisfy the bundle constramts.

• For example for the problem we have just solved, with the optimal Lagrange multipliers  $w_{12} = 2$  and  $w_{s^1t^1} = 12$ , the shortest paths subproblems have solutions with 10 units on the path  $s^1 - t^1$  and 20 units on the path  $s^2 - t^2$ .

- This solution violates the capacity of the arc  $(s^1, t^1)$ .
- In general, to obtain optimal flows, even after we have solved the Lagrangian multiplier problem, requires additional work.

## The End